ERRATUM : MESH ADAPTIVE DIRECT SEARCH ALGORITHMS FOR CONSTRAINED OPTIMIZATION∗

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Abstract. In [SIAM J. Optim., 17 (2006), pp. 188-217] Audet and Dennis proposed the class of mesh adaptive direct search algorithms (MADS) for minimization of a nonsmooth function under general nonsmooth constraints. The notation used in the paper evolved since the preliminary versions and, unfortunately, even though the statement of Proposition 4.2 is correct, is not compatible with the final notation. The purpose of this note is show that the proposition is valid.

Key words. mesh adaptive direct search algorithms (MADS), constrained optimization, nonsmooth optimization

AMS subject classifications. 90C30, 90C56, 65K05, 49J52

In [1] Audet and Dennis proposed the class of mesh adaptive direct search algorithms (MADS) for minimization of a nonsmooth function under general nonsmooth constraints. The paper contains a convergence analysis for this class of methods, and proposes two variants of an implementable instance called LTMADS.

The proof that LTMADS is indeed an instance of MADS is not compatible with the notation used in the rest of the paper. We restate the proposition and propose a consistent proof.

Proposition 0.1 (Proposition 4.2 of [1]). At each iteration $k$, the procedure above yields a $D_k$ and a MADS frame $P_k$ such that

$$P_k = \{ x_k + \Delta_{mk} d : d \in D_k \} \subset M_k,$$

where $\Delta_{mk} > 0$ is the mesh size parameter, $M_k$ is given by Definition 2.1 of [1] and $D_k$ is a positive spanning set such that for each $d \in D_k$,

- $d$ can be written as a nonnegative integer combination of the directions in $D$: $d = Du$ for some vector $u \in \mathbb{N}^{n_D}$ that may depend on the iteration number $k$;
- the distance from the frame center $x_k$ to a frame point $x_k + \Delta_{mk} d \in P_k$ is bounded above by a constant times the poll size parameter: $\Delta_{mk} \|d\|_\infty \leq \Delta_p \max\{\|d'\|_\infty : d' \in D\}$;
- limits (as defined in Coope and Price [2]) of convergent subsequences of the normalized sets $\overline{D}_k := \{ \frac{d}{\|d\|_\infty} : d \in D_k \}$ are positive spanning sets.

Proof. In order to construct the set of directions $D_k$, the algorithm builds matrices at iteration $k$ that should be called $L_k, B_k$ and $B'_k$. To ease the presentation, we omit the index $k$ in the proof of the two first bullets. The index $k$ reappears in the proof of the last bullet since this last result involves limits as $k$ goes to infinity.

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By the construction in [1], \( L \) is a lower triangular \((n-1) \times (n-1)\) matrix where each term on the diagonal is either plus or minus \(2^\ell\), and the lower components are randomly chosen from the discrete set \([-2^\ell + 1, -2^\ell + 2, \ldots, 2^\ell - 1]\), with \(\ell\) an integer that satisfies \(2^\ell = \frac{1}{\sqrt{\Delta_k^n}}\). The rules for updating the mesh size parameter \(\Delta_k^n\) ensure that \(\ell \in \mathbb{N}\). It follows that \(L\) is a basis in \(\mathbb{R}^{n-1}\) with \(|\det(L)| = 2^{\ell(n-1)}\). Let \(\{p_1, p_2, \ldots, p_{n-1}\}\) be a random permutation of the set \(\{1, 2, \ldots, n\} \setminus \{i\}\), where \(\{i\}\) is defined in [1]. The elements of the matrix \(B\) are defined as

\[
B_{p_i,j} = L_{i,j} \quad \text{for } i, j = 1, 2, \ldots, n-1
\]

\[
B_{i,j} = 0 \quad \text{for } j = 1, 2, \ldots, n-1
\]

\[
B_{i,n} = b_i(\ell) \quad \text{for } i = 1, 2, \ldots, n,
\]

where \(b_i(\ell)\) is a vector that depends only on the value of the mesh size parameter, and not on the iteration number (see Subsection 4.1 of [1]). It follows that \(B\) is a permutation of the rows and the columns of a lower triangular matrix whose diagonal elements are either \(-2^\ell\) or \(2^\ell\). Therefore \(B\) is a basis in \(\mathbb{R}^n\) and \(|\det(B)| = 2^{\ell n}\).

The square matrix \(B'\) is obtained by permuting the columns of \(B\), and therefore the columns of \(B'\) form a basis of \(\mathbb{R}^n\). Furthermore, \(|\det(B')| = |\det(B)| = 2^{\ell n}\). One of the proposed versions of LTMADS uses a minimal positive basis at every iteration, and the other variant uses a maximal positive basis at every iteration. The columns of \([B' - b]\) with \(b' = \sum_{j \in \mathbb{N}} B'_{ij}\) define a minimal positive basis, and the columns of \([B' - B']\) define a maximal positive basis [3].

Therefore, if \(D_k = [B' - b]\) or if \(D_k = [B' - B']\), then all entries of \(D_k\) are integers in the interval \([-n2^\ell, n2^\ell]\) or in the interval \([-2^\ell, 2^\ell]\), respectively. It follows that each column \(d\) of \(D_k\) can be written as a nonnegative integer combination of the columns of \(D = [I - I]\). Hence, the frame defined by \(D_k\) is on the mesh \(M_k\).

Two cases must be considered to show the second bullet. Recall that with LTMADS, the poll size parameter \(\Delta_k^n\) (see [1]) is defined differently depending on whether minimal or maximal positive bases are used. If the maximal positive basis construction is used, then \(|\Delta_k^n d|_{\infty} = \Delta_k^n ||d||_{\infty} = \sqrt{\Delta_k^n} = \Delta_k^n\). If the minimal positive basis construction is used, then \(|\Delta_k^n d|_{\infty} = \Delta_k^n ||d||_{\infty} \leq n \sqrt{\Delta_k^n} = \Delta_k^n\). The proof of the second bullet follows by noticing that \(\max\{||d'||_{\infty} : d' \in [I - I]\} = 1\).

To show the third bullet, we will verify that the limit of the normalized sets

\[
\overline{D_k} := \{ \frac{d}{||d||_{\infty}} : d \in D_k \}
\]

forms a positive basis. It suffices to show that the conditions (1a), (1b) and (C1) or (C2) of Coope and Price [2] hold.

- Conditions (1a) and (1b) ensure that the limit of any convergent subsequence of the sequence of bases \(\overline{B'_k} := \{ \frac{d}{||d||_{\infty}} : d \in B'_k \}\) is also a basis. Condition (1a) requires that \(|\det(\overline{B'_k})|\) be bounded below by a positive constant that is independent of \(k\). In our context, \(|\det(\overline{B'_k})| = 1\) for all \(k\), and therefore this condition is satisfied. Condition (1b) is also easily satisfied since normalized directions are used. It follows that the limit of \(\overline{B'_k}\) is a basis.

- Conditions (C1) and (C2) involve the columns added to each basis \(B'_k\) to form a positive basis. In the case of the maximal bases, condition (C1) is easily satisfied. For the minimal bases, (C2) holds since all the structure constants \(\xi\) (again following the definition of Coope and Price [2]) satisfy \(-1 \leq \xi \leq -\frac{1}{n}\).
REFERENCES

